UCLouvain

Where and with whom: Using Bayesian inference and deep learning to study protein localisation and protein-protein interactions

Laurent Gatto 21 December 2020 In biology, localisation of and interaction among proteins define their functions and activity. These information can be assayed experimentally and extracted from public databases. In this talk, I will present two use-cases, using Bayesian inference and deep learning, to infer protein sub-cellular localisation from experimental data and publicly available annotation.

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Outline

Scientific question: where, with whom

Experimental and annotation data

Data analysis (overview)

Bayesian inference

Deep learning

Conclusions

Cell organisation - localisation is function



Spatial proteomics is the systematic study of protein localisations.

Localisation - interactions - re-localisation - mis-localisation

Image from Wikipedia http://en.wikipedia.org/wiki/Cell_(biology).

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- On protein localisation
 - targetted microscopy-based
 - global protein localisation map
- On protein-protein interactions (PPI)

Fusion proteins and immunofluorescence



Figure: Targeted protein localisation. Example of discrepancies between IF and FPs as well as between FP tagging at the N and C termini (Stadler et al., 2013).

Explorative/discovery approaches, steady-state global localisation maps (as opposed to targeted microscopy-based approaches).

Density gradient: PCP (Dunkley et al., 2006), LOPIT (Foster et al., 2006), hyperLOPIT (Christoforou et al., 2016; Mulvey et al., 2017) and **Differential centrifugation** Itzhak et al. (2016), LOPIT-DC (Geladaki et al., 2019).



	$Fraction_1$	$Fraction_2$		$Fraction_{L}$
x ₁	<i>x</i> _{1,1}	<i>x</i> _{1,2}		<i>x</i> _{1,L}
x ₂	x _{2,1}	<i>x</i> _{2,2}		<i>x</i> _{2,L}
x 3	x _{3,1}	X3,2		<i>x</i> 3,L
÷	:	:	÷	÷
xi	<i>x</i> _{i,1}	<i>x</i> _{i,2}		x _{i,L}
÷	:	÷	÷	÷
х _N	x _{N,1}	<i>x</i> _{N,2}		X _{N, L}

	Fraction ₁	$Fraction_2$		$Fraction_{L}$	markers
x ₁	x _{1,1}	<i>x</i> _{1,2}		<i>x</i> _{1,L}	unknown
x ₂	x _{2,1}	<i>x</i> _{2,2}		<i>x</i> _{2,L}	loc1
x 3	x _{3,1}	<i>x</i> _{3,2}		<i>x</i> 3,L	unknown
:	÷	÷	÷	÷	:
xi	<i>x</i> _{i,1}	<i>x</i> _{i,2}		x _{i,L}	lock
:	:	÷	÷	÷	:
\mathbf{x}_{N}	x _{N,1}	x _{N,2}		<i>х</i> N, К	unknown



Figure: From Gatto et al. (2010), *Arabidopsis thaliana* data from Dunkley et al. (2006)

Protein-protein interactions

Affinity purification mass spectometry (AP-MS). The bait protein (yellow) is immobilised on a matrix (1). A protein mixture is passed through and only the interacting partners (prey) are retained (2). Then the prey proteins are eluded, digested and analysed by mass spectrometry (3).



We have used the Bioplex (Huttlin et al., 2020) data (https://bioplex.hms.harvard.edu/).

Extracted from public repositories:

- Gene Ontology (GO) knowledgebase is the world's largest source of information on the functions of genes. (Ashburner et al., 2000). Terms (biological process, molecular signature, cellular compartment) represented as directed acyclic graphs (DAG).
- Human Proteome Atlas (HPA) maps all the human proteins in cells, tissues and organs using an integration of various omics technologies, including antibody-based imaging, mass spectrometry-based proteomics, transcriptomics and systems biology. (Uhlén et al., 2005; Uhlen et al., 2010) The Cell Atlas provides high-resolution insights into the expression and spatio-temporal distribution of RNA and proteins in human cell lines.

• **STRING** is a database of known and predicted protein-protein interactions. The interactions include direct (physical) and indirect (functional) associations; they stem from computational prediction, from knowledge transfer between organisms, and from interactions aggregated from other (primary) databases. (Szklarczyk et al., 2018)

Experimental data \neq annotation data

 $\mathsf{Specific} \neq \mathsf{generic}$

(Expected) high quality \neq unknown quality

Expensive to produce \neq free to consome

Generally small \neq big data

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Computational challenges

- Visualisation (unsupervised learning) (Gatto et al., 2014, 2019)
- Classification (Gatto et al., 2014)
- Novelty detection (semi-supervised learning) (Breckels et al., 2013; Crook et al., 2020)
- Uncertainty quantification (Crook et al., 2018)
- Multi-localisation (Crook et al., 2018)
- Spatial dynamics
- Data integration (transfer learning) (Breckels et al., 2016)
- Deep learning

To uncover and understand biology

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Supervised Machine Learning



Figure: Support vector machines classifier (after 5% FDR classification cutoff) on the embryonic stem cell data from Christoforou et al. (2016).

How much do we learn? How much do we miss?



Bayesian Mixture Modelling For Spatial Proteomics

• *T* Augmented Gaussian Mixture model (TAGM) is a **multivariate** Gaussian generative model for MS-based spatial proteomics data. It posits that each annotated sub-cellular niche can be modelled by a multivariate Gaussian distribution.

Bayesian Mixture Modelling For Spatial Proteomics

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- With the prior knowledge that many proteins are not captured by known sub-cellular niches, we augment our model with an **outlier component**. Outliers are often dispersed and thus this additional component is described by a heavy-tailed distribution: the multivariate Student's t-distribution, leading us to a *T* Augmented Gaussian Mixture model (Crook et al., 2018, 2019).

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- This methodology allows proteome-wide **uncertainty quantification**, thus adding a further layer to the analysis of spatial proteomics.

$$\mathbf{x}_i | z_i = k \quad \sim \mathcal{N}(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$
 (1)

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 (1)

$$\mathbf{x}_i | \mathbf{z}_i = k, \phi_i \quad \sim \mathcal{N}(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)^{\phi_i} \mathcal{T}(\kappa, \boldsymbol{M}, \boldsymbol{V})^{1 - \phi_i}$$
(2)



Figure: Assignment of proteins of *unknown* location to one of the annotated classes. The dots are scaled according to the protein assignment probabilities.





Distribution of Subcellular Membership for Protein Q924C1

Figure: Exportin 5 (Q924C1) forms part of the micro-RNA export machinery, transporting miRNA from the nucleus to the cytoplasm for further processing. It then translocates back through the nuclear pore complex to return to the nucleus to mediate further transport between nucleus and cytoplasm. The model correctly infers that it most likely localises to the cytosol but there is some uncertainty with this assignment. This uncertainty is reflected in possible assignment of Exportin 5 to the nucleus non-chromatin and reflects the multi-location of the protein.

Whole sub-cellular proteome uncertainty



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- STRING database (PPI, annotation): 3,121,320 pairwise interactions.
- Bioplex (PPI, large experimental resource): 64,861 pairwise interactions.
- Human protein atlas (localisation, large experimental resource): assigned to 28 reliable locations.

	source	protein1	protein2
1	string	ENSP00000310301	ENSP00000388940
2	string	ENSP00000379658	ENSP00000394560
3	string	ENSP00000360112	ENSP00000360312
4	bioplex	ENSP00000294889	ENSP00000304586
5	bioplex	ENSP00000261531	ENSP00000252011

	location1	location2
1		
2	{'Nucleoli', 'Cytosol'}	
3	{'Nucleoplasm'}	
4		{'Nucleoplasm', 'Cytosol'}
5	{'Nucleoplasm', 'Cytosol'}	{'Nucleoplasm', 'Nuclear bodies', 'Centrosome'}

	combined_score	locations $(loc_1 \cap loc_2)$	
1	0.23		new finding
2	0.21	{'Nucleoli', 'Cytosol'}	filtering
3	0.25	{'Nucleoplasm'}	filtering
4	1.00	{'Nucleoplasm', 'Cytosol'}	filtering
5	1.00	{'Nucleoplasm'}	always included



Calculate the normalized frequency count and retain the annotations up to the cumulative threshold.

- Location observations: p_i : $(loc_1, loc_2), (loc_1)$ and (loc_1, loc_2, loc_3) .
- Location frequencies: *loc*₁: 0.5, *loc*₂: 0.333 and *loc*₃: 0.167.
- Retained locations for a threshold of 0.85: loc_1 and loc_2



Multilabel classification



Figure: 28 binary classifiers each of which predicts the output of a single location.



Figure: LSTM cell followed by the fully-connected layer that reduces the hidden dimension to 2 with the softmax activation function (based on Pan et al. (2019)).

Multilabel classification (DAG)



Figure: 28 locations of interest are not independent! These dependencies, based on the GO DAGS are incorporated while making predictions (dotted lines).





DAG structure (3)







Figure: Model hyperparameters optimisation: number of epochs and 28 class thresholds (aggregated binary cross-entropy loss).

Preliminary results

Data	Filtering	Thresholding (% retained)	Loss	Accuracy	Sensitivity	Specificity	AUC-ROC	# data points (approx)
Combined	-	100	0.09211198312	0.8958986402	0.9571145481	0.6061253268	0.7816199375	65000
Combined	After node2vec	100	0.06054629228	0.970810473	0.9872313536	0.6738782051	0.8305547794	65000
Combined	Before node2vec	100	0.03273588772	0.9793367386	0.9918602378	0.8043154762	0.898087857	65000
Combined	-	70	0.08751676821	0.9372128248	0.9737043101	0.6011392776	0.7874217939	65000
Combined	After node2vec	70	0.05432904263	0.9745306969	0.9885046844	0.687366453	0.8379355687	65000
Combined	Before node2vec	70	0.02413146035	0.9863733053	0.9937820852	0.8583333333	0.9260577093	65000
Combined	-	100	0.08841074915	0.8633737564	0.9440426985	0.611838943	0.7779408208	150000
Combined	After node2vec	100	0.0515132316	0.9673402309	0.9871013833	0.6383223684	0.8127118758	150000
Combined	Before node2vec	100	0.03110835513	0.9817546606	0.9938010343	0.8235960145	0.9086985244	150000
Combined	-	70	0.08060763591	0.9333102703	0.9724473643	0.6090694232	0.7907583938	150000
Combined	After node2vec	70	0.0303748032	0.9744595885	0.9905288649	0.657127193	0.8238280289	150000
Combined	Before node2vec	70	0.01893794582	0.9898679852	0.9955202527	0.8930253623	0.9442728075	150000

- First iteration with the full dataset, after filtering, threshold of 0.6: AUC-ROC of 0.92.
- Biological findings: make inferences on the unannotated dataset.

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- From data to biology and medicine.
- Interpretability is important; experimental vs. annotation.
- Interdisciplinary and collaborative work.



Thank you for your attention

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